

# LSI Series

## DC-Operated, Gravity-Referenced Servo Inclinometer



### Features

- Fully self-contained - connect to a DC power source and a readout or control device for a complete operating system
- High-level DC output signal proportional to sine of the angle of tilt
- $\pm 14.5^\circ$ ,  $\pm 30^\circ$  &  $\pm 90^\circ$  ranges available

### Benefits

- Economically Priced
- High Accuracy
- $-20^\circ\text{C}$  to  $+80^\circ\text{C}$  Temp Rating

### Applications

Level control of machines and structures

Marine ballast transfer systems

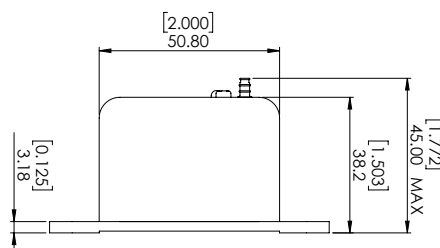
Civil engineering studies

Vehicle Wheel Alignment

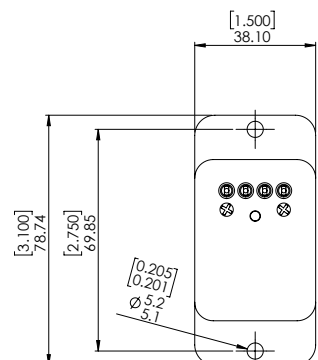
### Electrical Connections

Pin A	+ve Supply
Pin B	-ve Supply <i>(0V supply on 9 to 36 Vdc)</i>
Pin C	0V Common <i>(0V signal on 9 to 36 Vdc)</i>
Pin D	Signal Output

SIDE VIEW



PLAN VIEW



## Specifications

### Specifications by Range @ +20°C

		± 14.5°	± 30°	± 90°
Output Impedance	Ω (nom)		Less than 10	
Non-linearity (see note 2)	% FRO (max)	0.02	0.02	0.05
Cross-axis Sensitivity (see note 3)	% FRO (max)		± 1	
Zero Offset (see note 4)	Volts dc (max)		± 0.050	
Thermal Zero Shift	%FRO/°C (max)		± 0.003	
Thermal Sensitivity Shift	%Reading/°C (max)		± 0.01	

### Electrical

Full Range Output (FRO) (see note 1)	Volts dc	±5 ±0.5%
Excitation Voltage	Volts dc	±15 or +9 to +36
Power Consumption	W (max)	±15V version = ±0.6 +9V to +36V version = 1.5

### Environmental Characteristics

Operating Temperature Range °C	-20 to 80
Survival Temperature Range °C	-40 to 90
Shock Survival	500g, 0.5msec, ½ sine

## Notes

1. Full Range Output is defined as the full angular excursion from positive to negative, i.e. ±90° = 180°.
2. Non-linearity is determined by the method of least squares.
3. Cross-axis Sensitivity is the output of unit when tilted to full range angle in cross-axis.
4. Zero offset is specified under static conditions with no vibration inputs.

## Model Designation & Ordering Code

